

**Nonlinear evolution of
pressure gradient driven modes
and anomalous transport in plasmas**

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outline

1. Formulation: MHD
2. Rayleigh-Taylor instability
3. Rayleigh-Bénard convection
4. Resistive interchange mode
5. Nonlinear analyses and bifurcation
6. tearing modes of multiple rational surfaces
7. Nonlinear evolution of multiple tearing modes
8. Summary

MHD equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\rho \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p + \mathbf{j} \times \mathbf{B} + \nu \Delta \mathbf{v}$$

$$\frac{\partial p}{\partial t} + \mathbf{v} \cdot \nabla p + \gamma p \nabla \cdot \mathbf{v} = \kappa \Delta p$$

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B} - \eta \mathbf{j})$$

$$\mu_0 \mathbf{j} = \nabla \times \mathbf{B} \quad \nabla \cdot \mathbf{B} = 0$$

Fluid dynamics equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\rho \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p - \rho g \mathbf{z} + \nu \Delta \mathbf{v}$$

$$\frac{\partial T}{\partial t} + \mathbf{v} \cdot \nabla T + (\gamma - 1) \gamma T \nabla \cdot \mathbf{v} = \kappa \Delta T$$

$$p = p(\rho, T)$$

with the gravitational field in the negative z direction

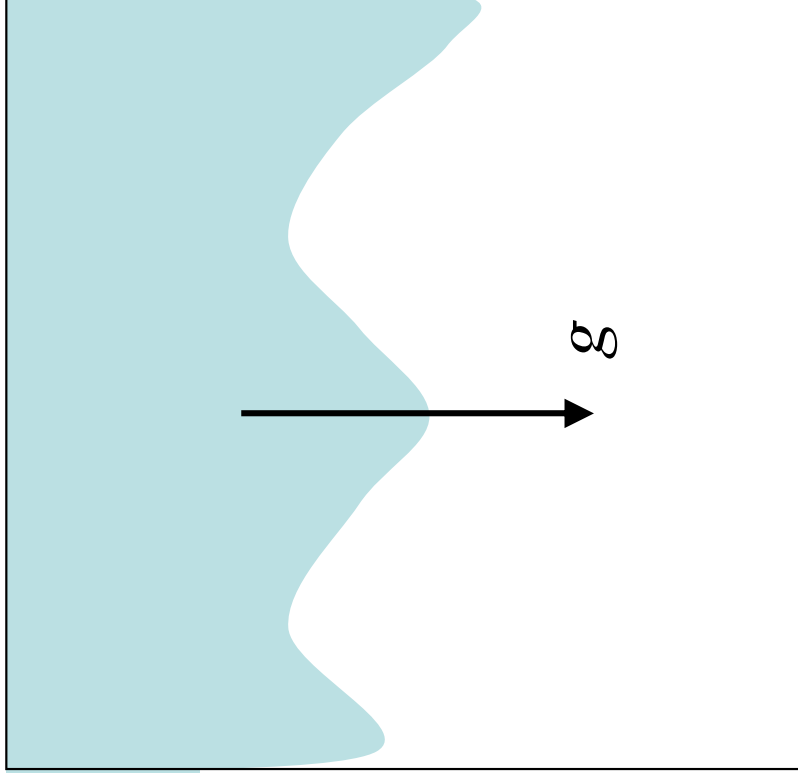
Rayleigh-Taylor instability

$$\frac{\partial \rho}{\partial t} + \mathbf{v} \cdot \nabla \rho = 0$$

$$\nabla \cdot \mathbf{v} = 0$$

$$\rho \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p - \rho g \mathbf{z}$$

incompressibility is assumed



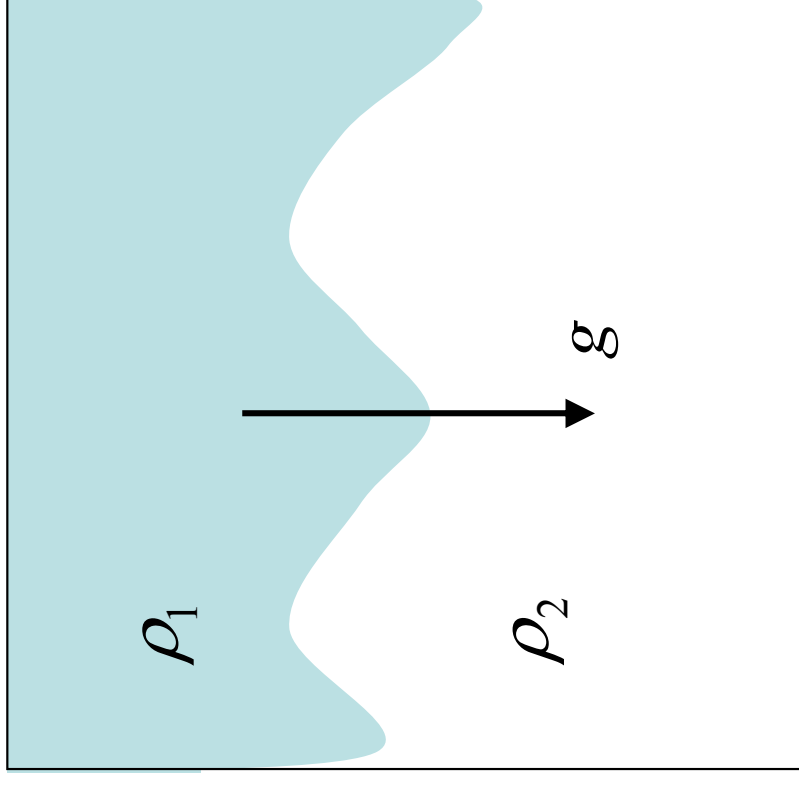
Rayleigh-Taylor instability

often analyzed for two separate fluids

$$\rho = \rho_1 \quad \text{or} \quad \rho_2$$

$$\nabla \cdot \mathbf{v} = 0$$

$$\rho_i \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p - \rho_i g \mathbf{z}$$



Rayleigh Bénard convection

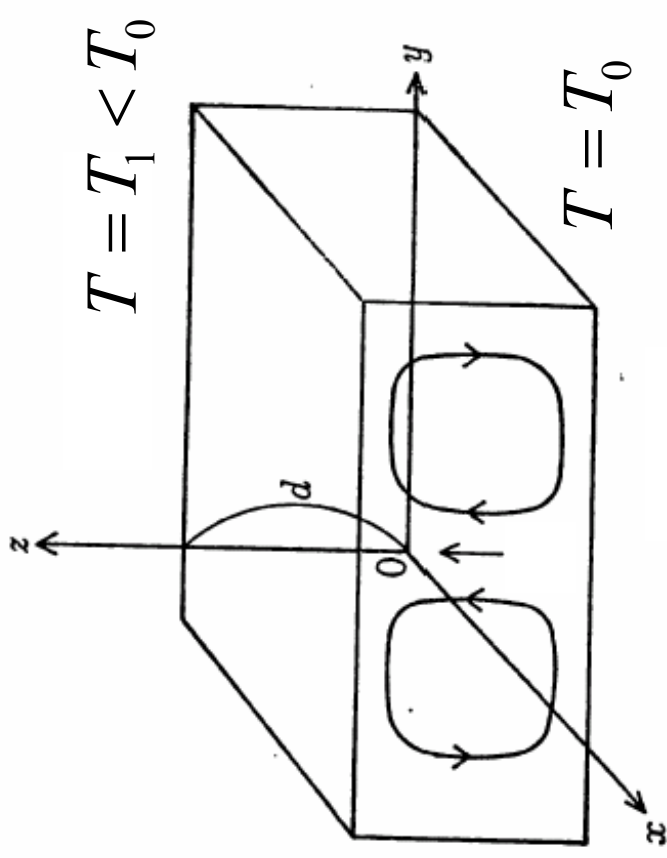
$$\nabla \cdot \mathbf{v} = 0$$

$$\rho_0 \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p - \rho g \hat{\mathbf{z}} + \nu \Delta \mathbf{v}$$

$$\rho(T) = \rho_0 [1 - \alpha (T - T_0)]$$

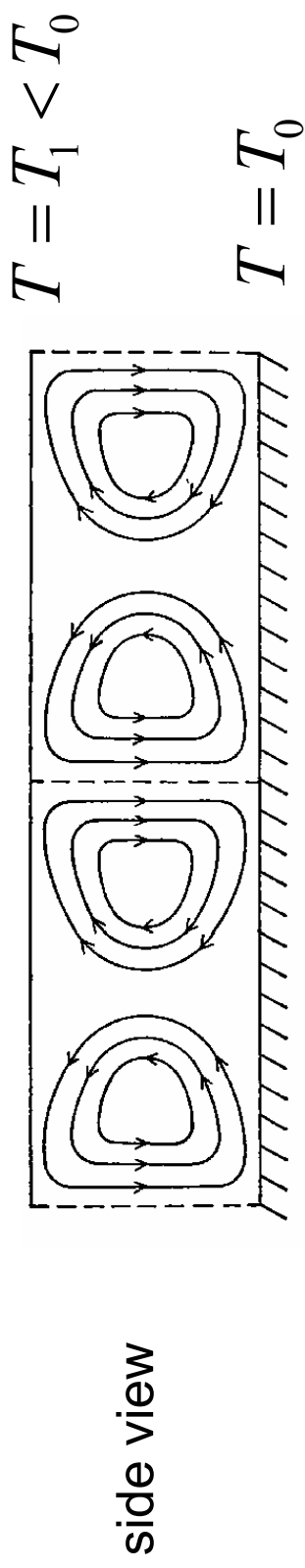
$$\frac{\partial T}{\partial t} + \mathbf{v} \cdot \nabla T = \kappa \Delta T$$

Boussinesq approximation

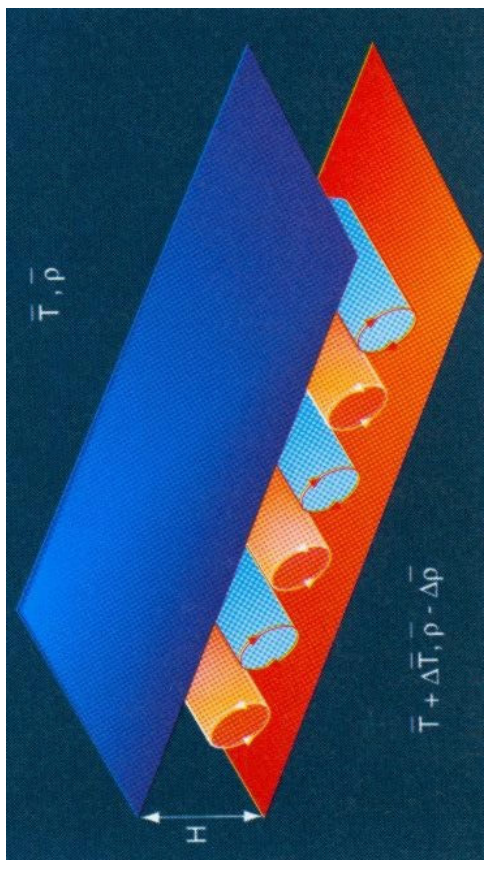
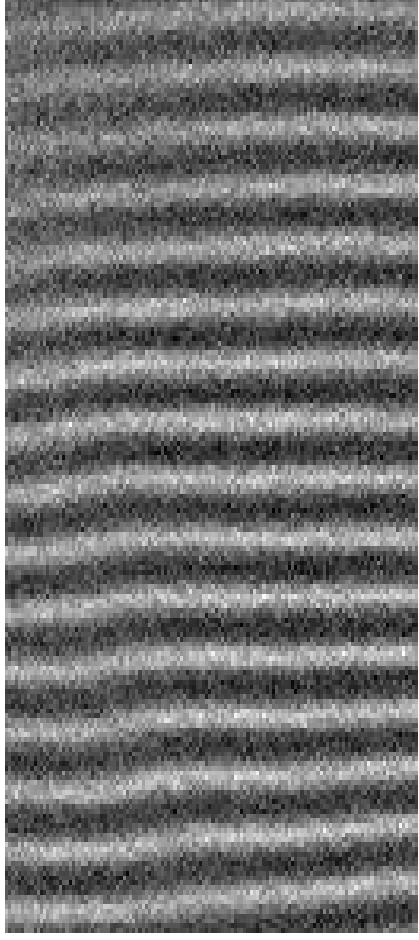


Rayleigh Bénard convection

2D convection : rolls

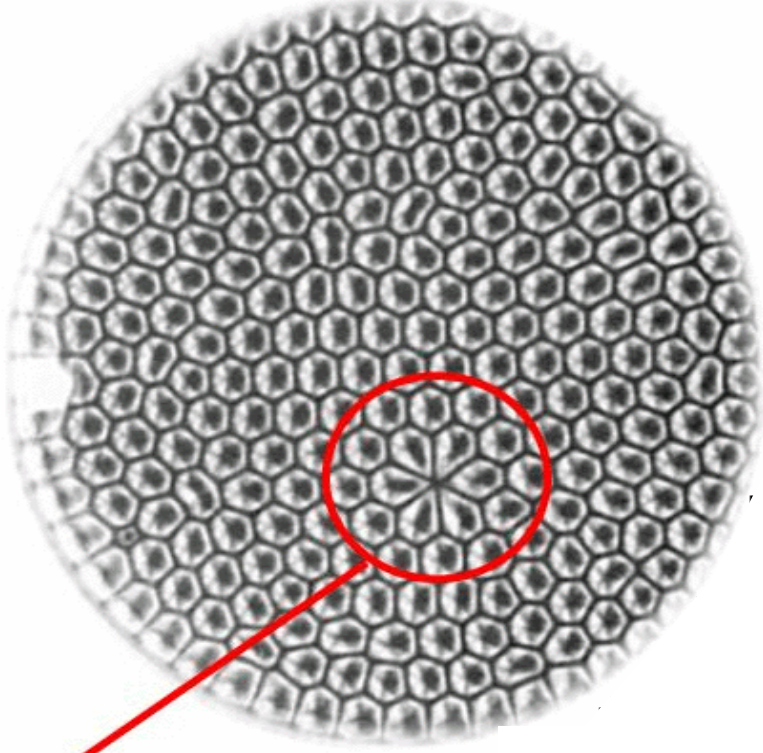
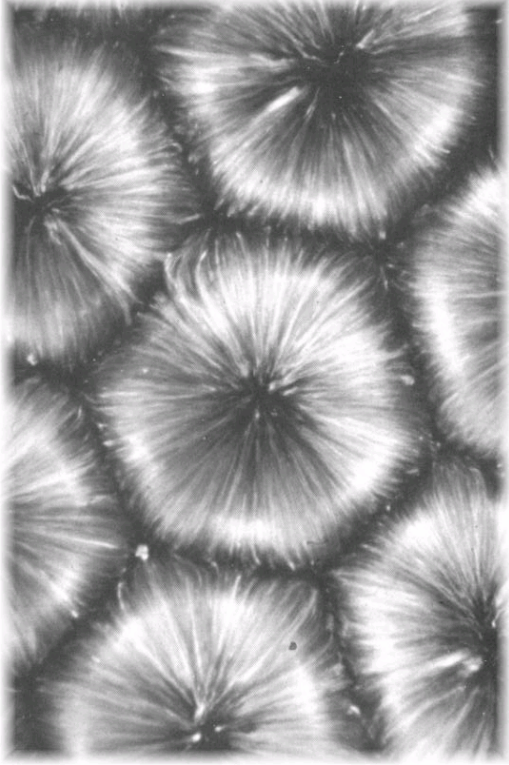


top view

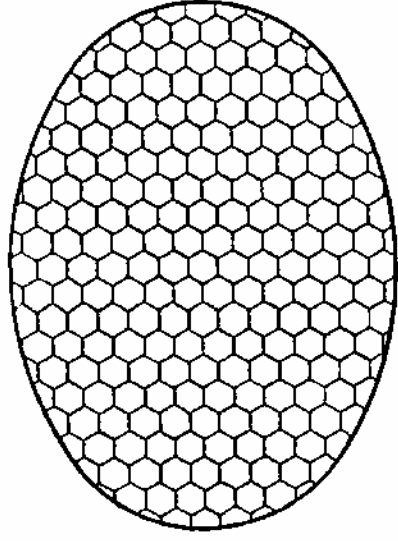


Rayleigh Bénard Convection

3D convection: hexagons
(with some defects)



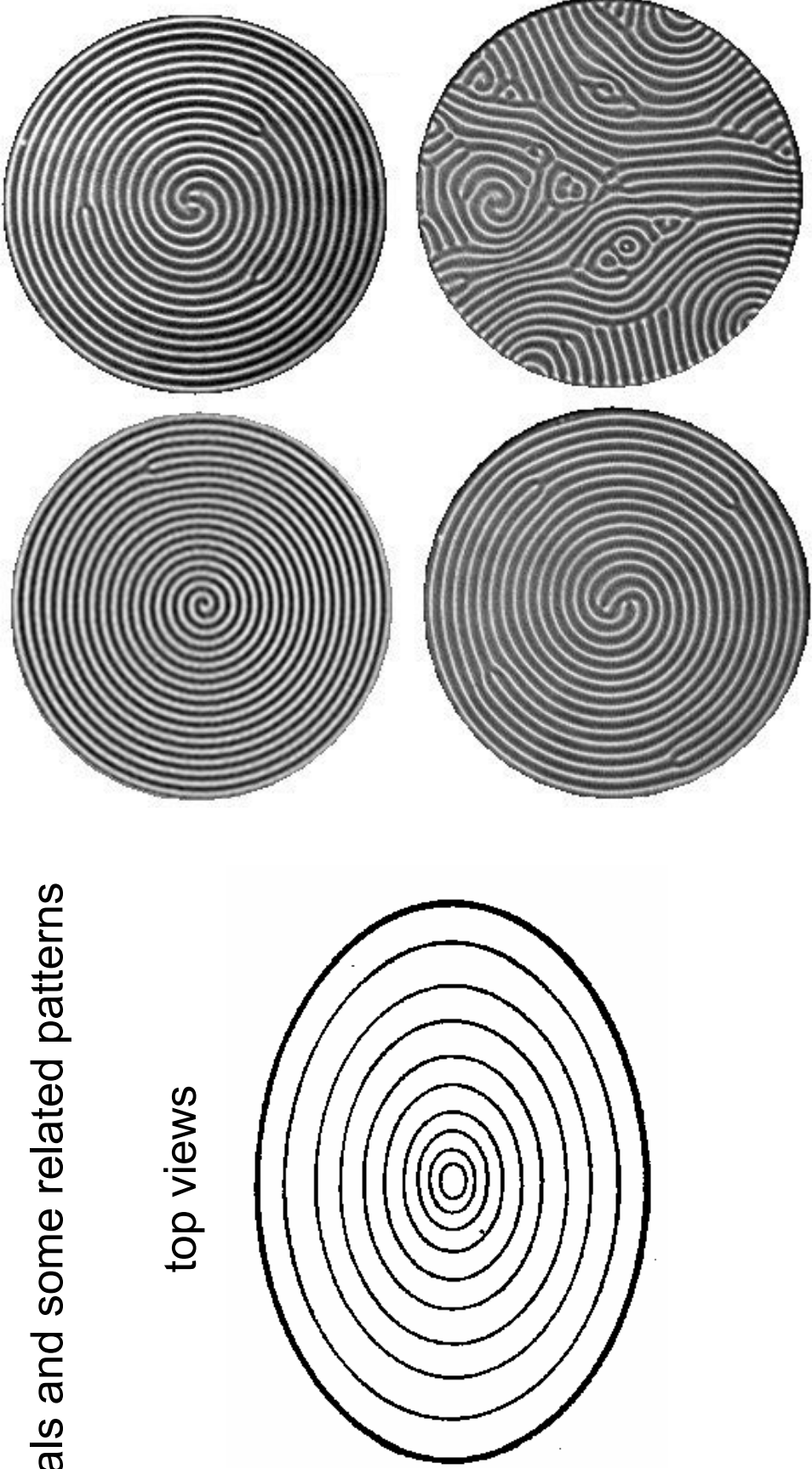
top views

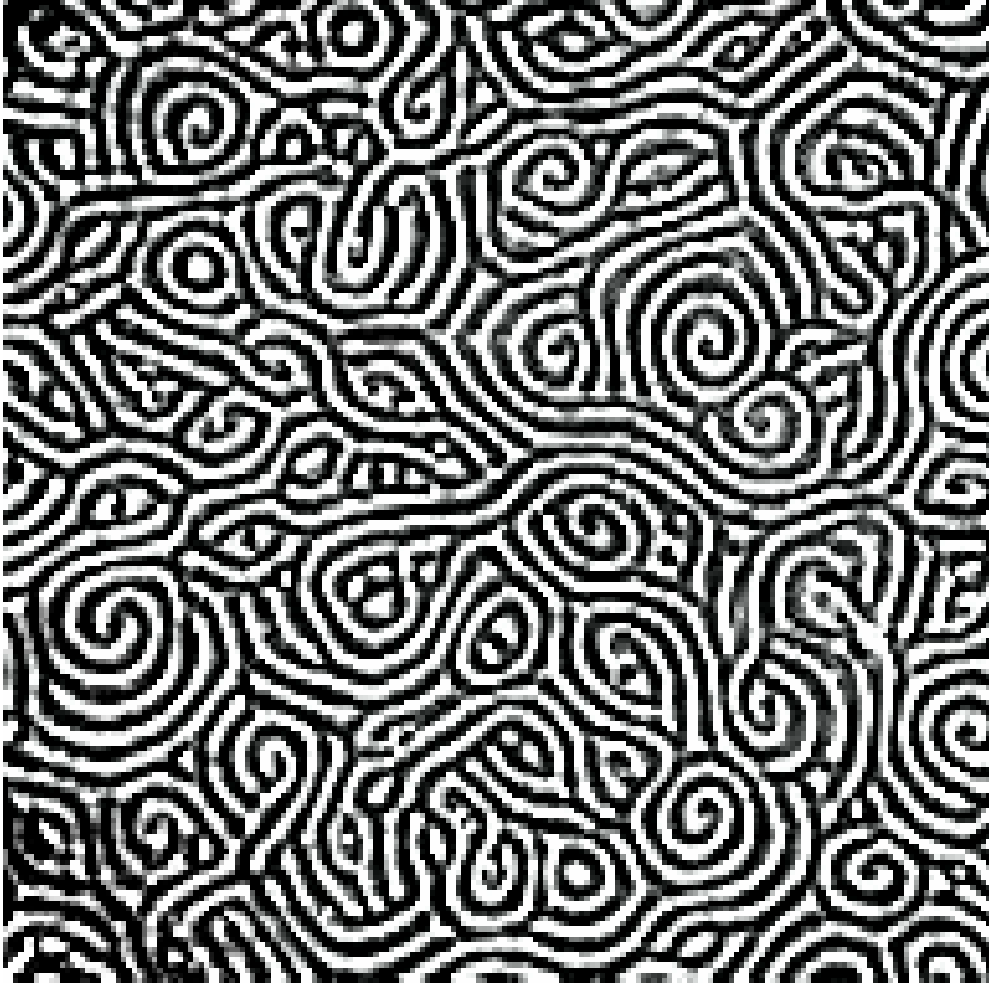


Rayleigh Bénard Convection

3D convections: more complicated patterns can appear
Spirals and some related patterns

top views





Defect chaos in Rayleigh-Benard convection

Stephen Morris at the University of Toronto <http://cnls.lanl.gov/~nbt/movies.html>

Rayleigh Bénard convection

Equilibrium Solution

$$\nabla \cdot \mathbf{v} = 0$$

$$\rho_0 \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p - \rho g \hat{\mathbf{z}} + \nu \Delta \mathbf{v}$$

$$\rho(T) = \rho_0 [1 - \alpha(T - T_0)]$$

$$\frac{\partial T}{\partial t} + \mathbf{v} \cdot \nabla T = \kappa \Delta T$$

Set $\mathbf{v} = 0$, $\frac{\partial}{\partial t} = 0$, z dependent only

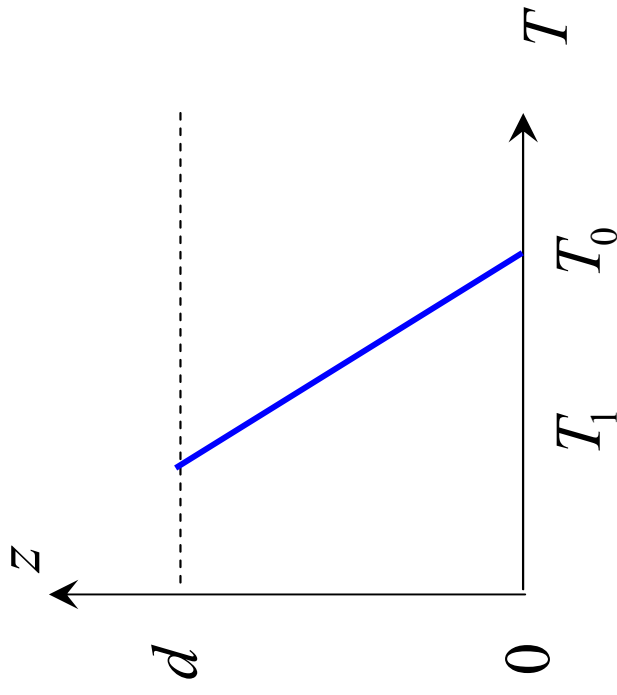
(with $\nu = \kappa = 0$)

Rayleigh Bénard convection

Equilibrium Solution

$$\bar{T} = T_0 - \beta z, \quad \beta = \frac{T_0 - T_1}{d} \quad (\text{temperature gradient})$$

$$\bar{p} = p_0 + \rho_0 g z \left(1 + \frac{\alpha \beta}{2} z \right)$$



Rayleigh Bénard convection equations for perturbation

By setting $\theta = T - \bar{T}(z)$ $\tilde{p} = p - \bar{p}(z)$

$$\nabla \cdot \mathbf{v} = 0$$

$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = - \frac{\nabla p}{\rho_0} + g\alpha\theta \mathbf{z} + \nu \Delta \mathbf{v}$$

we have rewritten

$$\frac{\nu}{\rho_0} \rightarrow \nu$$

$$\frac{\partial \theta}{\partial t} + \mathbf{v} \cdot \nabla \theta = \beta w + \kappa \Delta \theta$$

$$w = \mathbf{v} \cdot \mathbf{z} \quad (\text{i.e., } z \text{ component of } \mathbf{v})$$

$$\theta(t, x, y, 0) = \theta(t, x, y, d) = 0 \quad (\text{Boundary conditions})$$

Rayleigh Bénard convection normalized equations

By setting

$$v \rightarrow \frac{v}{d}$$

$$\theta \rightarrow \frac{\beta d v}{\kappa} \theta$$

$$\tilde{p} \rightarrow \frac{\rho_0 v^2}{d^2} p$$

$$t \rightarrow \frac{d^2}{\kappa} t$$

$$(x, y, z) \rightarrow d(x, y, z)$$

$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} = -\nabla p + R \hat{\mathbf{z}} + \Delta \mathbf{v}$$

$$\frac{\partial \theta}{\partial t} + \mathbf{v} \cdot \nabla \theta = \frac{1}{P} w + \frac{1}{P} \Delta \theta$$

$$\nabla \cdot \mathbf{v} = 0$$

R : Rayleigh number

P : Prandtl number

Rayleigh Bénard convection

2D normalized equations

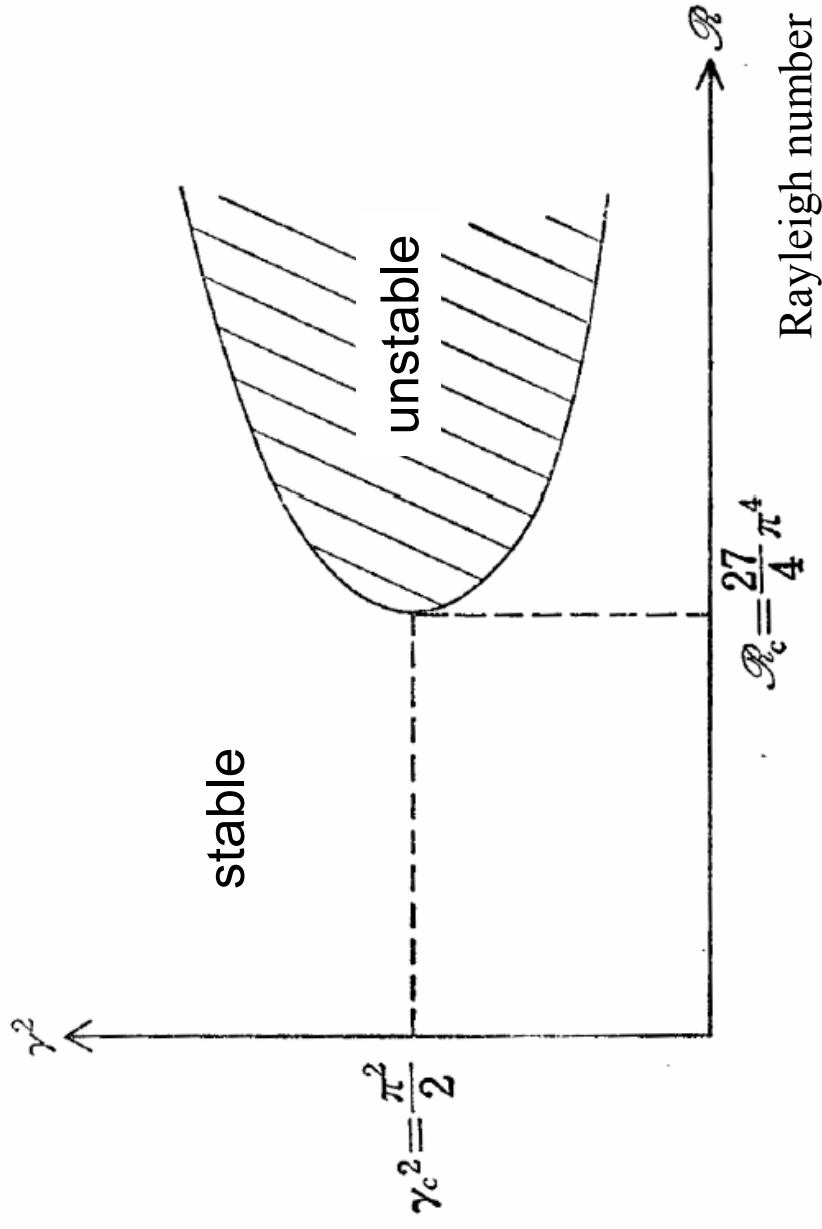
Consider only 2D solutions:

$$\mathbf{v} = \nabla \phi(y, z) \times \hat{\mathbf{x}} = \left(0, \frac{\partial \phi}{\partial z}, -\frac{\partial \phi}{\partial y} \right)$$

$$\left\{ \begin{array}{l} \frac{d}{dt} \Delta \phi = -R \frac{\partial \theta}{\partial y} + \Delta^2 \phi \\ \frac{d\theta}{dt} = -\frac{1}{P} \frac{\partial \phi}{\partial y} + \frac{1}{P} \Delta \theta \end{array} \right.$$

Rayleigh Bénard convection

Stability Analysis



Rayleigh Bénard convection

Heat Transfer

$$\text{Nusselt Number } Nu = \frac{\text{total heat transfer}}{\text{heat transfer at rest}} = \frac{H}{\kappa \rho_0 c_p (T_0 - T_1) / d}$$

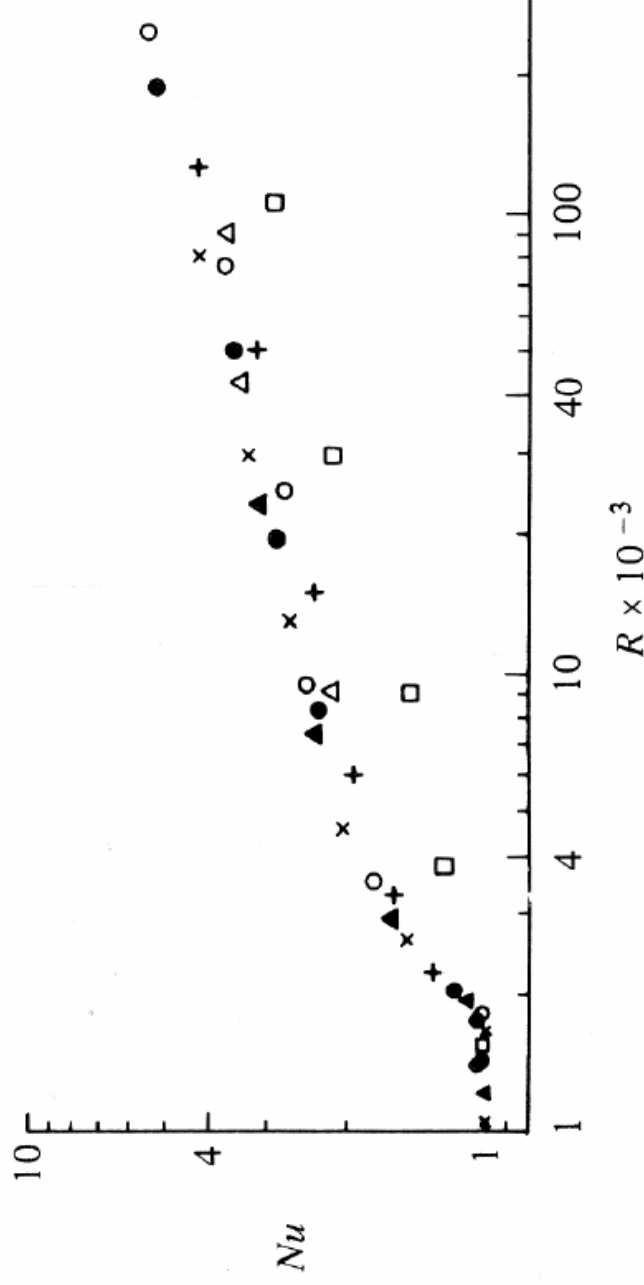


Fig. 2.6. Some experimental results on the heat transfer in various fluids in various containers. The Nusselt number is plotted against the Rayleigh number; O water; + heptane; x ethylene glycol; ● silicone oil AK 3; ▲ silicone oil AK 350; Δ air; □ mercury. After Silveston 1958 and Rossby 1969.)

From "Hydrodynamic stability" (Drazin & Reid)

Resistive interchange mode

$$\rho \left(\frac{\partial \mathbf{v}}{\partial t} + \mathbf{v} \cdot \nabla \mathbf{v} \right) = -\nabla p + \mathbf{j} \times \mathbf{B} + \nabla \cdot \mathbf{\Pi}$$

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B} - \eta \mathbf{j}) \quad \mu_0 \mathbf{j} = \nabla \times \mathbf{B} \quad \nabla \cdot \mathbf{B} = 0$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\frac{\partial p}{\partial t} + \mathbf{v} \cdot \nabla p + \gamma p \nabla \cdot \mathbf{v} = (\gamma - 1) \left[\eta \mathbf{j} \cdot \mathbf{j} + \nabla \cdot (\kappa \nabla T) - \mathbf{\Pi} : \nabla \mathbf{v} \right]$$

$$p = \rho T$$

$$\mathbf{\Pi} = -3\mu_{\parallel} \left(\hat{\mathbf{b}}\hat{\mathbf{b}} - \frac{1}{3}\mathbf{I} \right) \lambda - \mu_{\perp} \sigma \quad \lambda = \hat{\mathbf{b}} \cdot \left[(\hat{\mathbf{b}} \cdot \nabla) \mathbf{v} \right] - \frac{1}{3} \nabla \cdot \mathbf{v}$$

$$\sigma_{ij} = \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} - \frac{2}{3} \delta_{ij} \nabla \cdot \mathbf{v}$$

Resistive interchange mode

Equations for the mean fields

$$\nabla p_0 = \mathbf{j}_0 \times \mathbf{B}_0$$

$$\frac{\partial \mathbf{B}_0}{\partial t} = \nabla \times (\mathbf{u}_0 \times \mathbf{B}_0 + \boldsymbol{\varepsilon} - \eta \mathbf{j}_0) \quad \mu_0 \mathbf{j}_0 = \nabla \times \mathbf{B}_0 \quad \nabla \cdot \mathbf{B}_0 = 0$$

$$\frac{\partial \rho_0}{\partial t} + \nabla \cdot (\rho_0 \mathbf{u}_0) = 0$$

$$\frac{\partial p_0}{\partial t} + \mathbf{u}_0 \cdot \nabla p_0 + \gamma p_0 \nabla \cdot \mathbf{u}_0 = (\gamma - 1) \left[\eta \mathbf{j}_0 \cdot \mathbf{j}_0 + \nabla \cdot (\kappa \nabla T_0) - \nabla \cdot (p_0 \langle s_1 \mathbf{v}_1 \rangle) + f \right]$$

$$\mathbf{u}_0 = \mathbf{v}_0 + (1/\rho_0) \langle \rho_1 \mathbf{v}_1 \rangle \quad s \equiv [1/(\gamma - 1)] \log(p/\rho^\gamma)$$

$$\boldsymbol{\varepsilon} = \langle \mathbf{v}_1 \times \mathbf{B}_1 \rangle - (1/\rho_0) \langle \rho_1 \mathbf{v}_1 \rangle \times \mathbf{B}_0$$

$$f = -\nabla \cdot \langle (p_1 + \mathbf{B}_0 \cdot \mathbf{B}_1) \mathbf{v}_1 - (\mathbf{v}_1 \cdot \mathbf{B}_1) \mathbf{B}_0 + (1/2) \rho_0 \mathbf{v}_1^2 \cdot \mathbf{v} \rangle$$

Resistive interchange mode

Equations for fluctuating fields

$$\mathbf{B}_1 = \nabla_{\perp} A \times \mathbf{b} - p_1 \mathbf{b}$$

$$\mathbf{j}_1 = -(\nabla_{\perp}^2 A) \mathbf{b} - \nabla_{\perp} p_1 \times \mathbf{b}$$

$$\mathbf{v}_1 = \nabla_{\perp} \phi \times \mathbf{b} - v \mathbf{b}$$

$$\nabla_{\perp} \equiv \nabla - \mathbf{b}(\mathbf{B}_0 \nabla \cdot) \quad \mathbf{b} = \mathbf{B}_0 / |\mathbf{B}_0|^2$$

Resistive interchange mode

Equations for fluctuating fields

$$\frac{d\tilde{A}}{d\tau} = \frac{\partial\tilde{\phi}}{\partial\theta} + \frac{1}{R}\Delta_{\perp}\tilde{A}$$

$$\frac{d}{d\tau}\Delta_{\perp}\tilde{\phi} = \frac{\partial}{\partial\theta}\Delta_{\perp}\tilde{A} + \left\{\tilde{A}, \Delta_{\perp}\tilde{A}\right\} - \frac{\partial\tilde{p}}{\partial y} + M\Delta_{\perp}^2\tilde{\phi}$$

$$\frac{d\tilde{p}}{d\tau} = -D\frac{\partial\tilde{\phi}}{\partial y} + \chi\Delta_{\perp}\tilde{p}$$

$$\frac{d\tilde{v}}{d\tau} = \frac{\partial\tilde{p}}{\partial\theta} + \left\{\tilde{A}, \tilde{p}\right\} + D\frac{\partial\tilde{A}}{\partial y} + M\Delta_{\perp}\tilde{v}$$

$$\frac{d}{d\tau} = \frac{\partial}{\partial\tau} + \left\{\phi, \right\} \quad D \propto -p'_0 = -\frac{dp_0}{dr} \Big|_{r=r_0}$$

Resistive interchange mode

Normalization

$$x = |\sigma|^{1/2} \left[(r - r_0) / r_0 \right]$$

$$y = (B_\theta / r_0 B) |\sigma|^{1/2} \left[z - \mu(r) \theta \right]$$

$$\tilde{\theta} = |\sigma| \theta$$

$$\tau = \left(B_\theta |\sigma| / r_0 \sqrt{\rho_0} \right) t$$

$$\mu(r) = \frac{r B_z}{B_\theta} \quad \sigma = \frac{B_\theta \mu'}{B}$$

parameters are all evaluated at $r = r_0$

Resistive interchange mode

$$\frac{d\tilde{A}}{d\tau} = \frac{\partial\tilde{\phi}}{\partial\theta} + \frac{1}{R}\Delta_{\perp}\tilde{A}$$

$$\frac{d}{d\tau}\Delta_{\perp}\tilde{\phi} = \frac{\partial}{\partial\theta}\Delta_{\perp}\tilde{A} + \left\{ \tilde{A}, \Delta_{\perp}\tilde{A} \right\} - \frac{\partial\tilde{p}}{\partial y} + M\Delta_{\perp}^2\tilde{\phi}$$

$$\frac{d\tilde{p}}{d\tau} = -D\frac{\partial\tilde{\phi}}{\partial y} + \chi\Delta_{\perp}\tilde{p}$$

$$\frac{d}{d\tau} = \frac{\partial}{\partial\tau} + \left\{ \phi, \right\} \quad D \propto -p'_0 = -\left. \frac{dp_0}{dr} \right|_{r=r_0}$$

Resistive interchange mode

electrostatic limit

$$\frac{d\tilde{A}}{d\tau} = \frac{\partial \tilde{\phi}}{\partial \theta} + \frac{1}{R} \Delta_{\perp} \tilde{A}$$

$$\frac{d}{d\tau} \Delta_{\perp} \tilde{\phi} = \frac{\partial}{\partial \theta} \Delta_{\perp} \tilde{A} + \left\{ \tilde{A}, \Delta_{\perp} \tilde{A} \right\} - \frac{\partial \tilde{p}}{\partial y} + M \Delta_{\perp}^2 \tilde{\phi}$$

$$\frac{d\tilde{p}}{d\tau} = -D \frac{\partial \tilde{\phi}}{\partial y} + \chi \Delta_{\perp} \tilde{p}$$

$$D \propto -p'_0 = - \left. \frac{dp_0}{dr} \right|_{r=r_0}$$

Resistive interchange mode

electrostatic limit

$$\frac{d}{d\tau} \Delta_{\perp} \tilde{\phi} = -R \frac{\partial^2}{\partial \tilde{\theta}^2} \tilde{\phi} - \frac{\partial \tilde{p}}{\partial y} + M \Delta_{\perp}^2 \tilde{\phi}$$

$$\frac{d \tilde{p}}{d\tau} = -D \frac{\partial \tilde{\phi}}{\partial y} + \chi \Delta_{\perp} \tilde{p}$$

Resistive interchange mode

electrostatic limit

$$\frac{d}{d\tau} \Delta_{\perp} \tilde{\phi} = -R \frac{\partial^2}{\partial \theta^2} \tilde{\phi} - \frac{\partial \tilde{p}}{\partial y} + M \Delta_{\perp}^2 \tilde{\phi}$$

$$\frac{d \tilde{p}}{d\tau} = -D \frac{\partial \tilde{\phi}}{\partial y} + \chi \Delta_{\perp} \tilde{p}$$

$$\left. \begin{aligned} \frac{d}{dt} \Delta \phi &= -R \frac{\partial \theta}{\partial y} + \Delta^2 \phi \\ \frac{d\theta}{dt} &= -\frac{1}{P} \frac{\partial \phi}{\partial y} + \frac{1}{P} \Delta \theta \end{aligned} \right\}$$

2D Rayleigh Bénard Convection

Resistive interchange mode

Alfvén wave

$$\frac{d\tilde{A}}{d\tau} = \frac{\partial\tilde{\phi}}{\partial\theta} + \frac{1}{R}\Delta_{\perp}\tilde{A}$$

$$\frac{d}{d\tau}\Delta_{\perp}\tilde{\phi} = \frac{\partial}{\partial\theta}\Delta_{\perp}\tilde{A} + \left\{\tilde{A}, \Delta_{\perp}\tilde{A}\right\} - \frac{\partial\tilde{p}}{\partial y} + M\Delta_{\perp}^2\tilde{\phi}$$

$$\frac{d\tilde{p}}{d\tau} = -D\frac{\partial\tilde{\phi}}{\partial y} + \chi\Delta_{\perp}\tilde{p}$$

Resistive interchange mode

Tearing mode

$$\frac{d\tilde{A}}{d\tau} = \frac{\partial\tilde{\phi}}{\partial\theta} + \frac{1}{R}\Delta_{\perp}\tilde{A}$$

$$\frac{d}{d\tau}\Delta_{\perp}\tilde{\phi} = \frac{\partial}{\partial\theta}\Delta_{\perp}\tilde{A} + \left\{\tilde{A}, \Delta_{\perp}\tilde{A}\right\} - \frac{\partial\tilde{p}}{\partial y} + M\Delta_{\perp}^2\tilde{\phi}$$

$$\frac{d\tilde{p}}{d\tau} = -D\frac{\partial\tilde{\phi}}{\partial y} + \chi\Delta_{\perp}\tilde{p}$$

Resistive interchange mode

bifurcation analysis

$$\frac{d\tilde{A}}{d\tau} = \frac{\partial\tilde{\phi}}{\partial\theta} + \frac{1}{R}\Delta_{\perp}\tilde{A}$$

$$\frac{d}{d\tau}\Delta_{\perp}\tilde{\phi} = \frac{\partial}{\partial\theta}\Delta_{\perp}\tilde{A} + \left\{\tilde{A}, \Delta_{\perp}\tilde{A}\right\} - \frac{\partial\tilde{p}}{\partial y} + M\Delta_{\perp}^2\tilde{\phi}$$

$$\frac{d\tilde{p}}{d\tau} = -D\frac{\partial\tilde{\phi}}{\partial y} + \chi\Delta_{\perp}\tilde{p}$$

Consider the case $\frac{\partial}{\partial t} = 0$

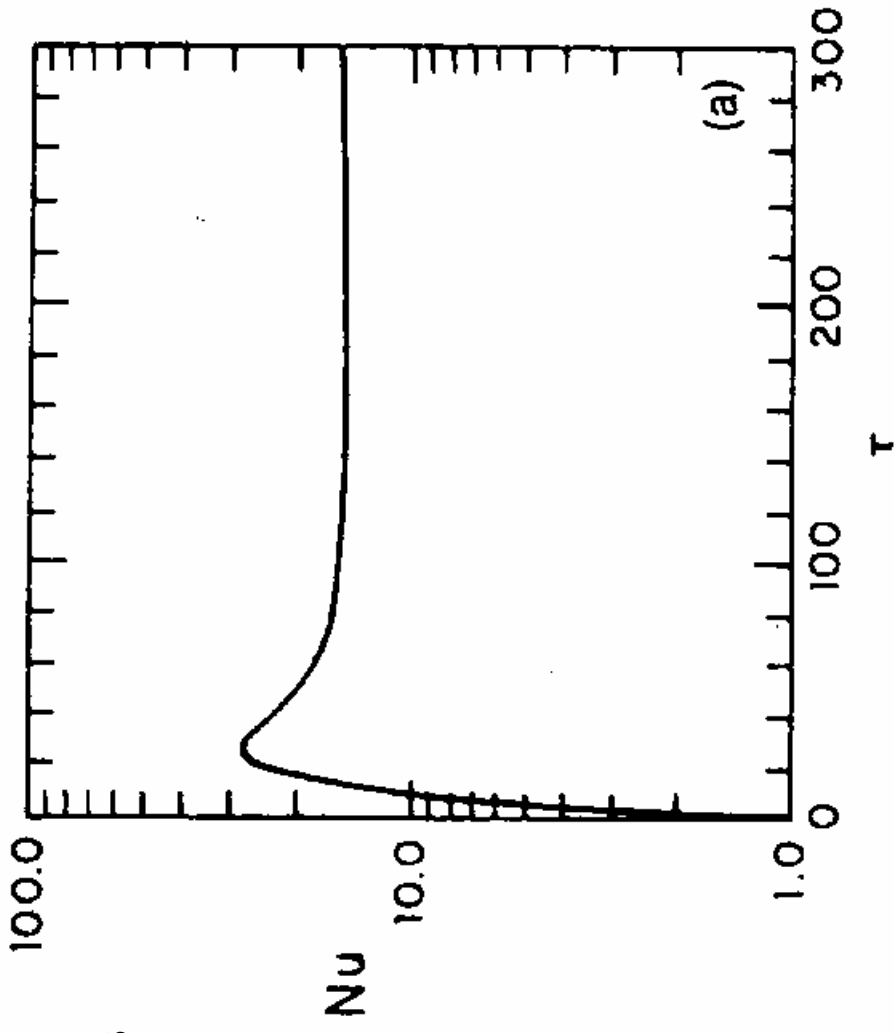
: steady state (i.e., mode saturation)

Resistive interchange mode

2D numerical simulation

$$D = 0.2 \quad M = 1 \quad K = 5 \times 10^{-3}$$

$D < 0.25$: ideal stability limit by
Suydam

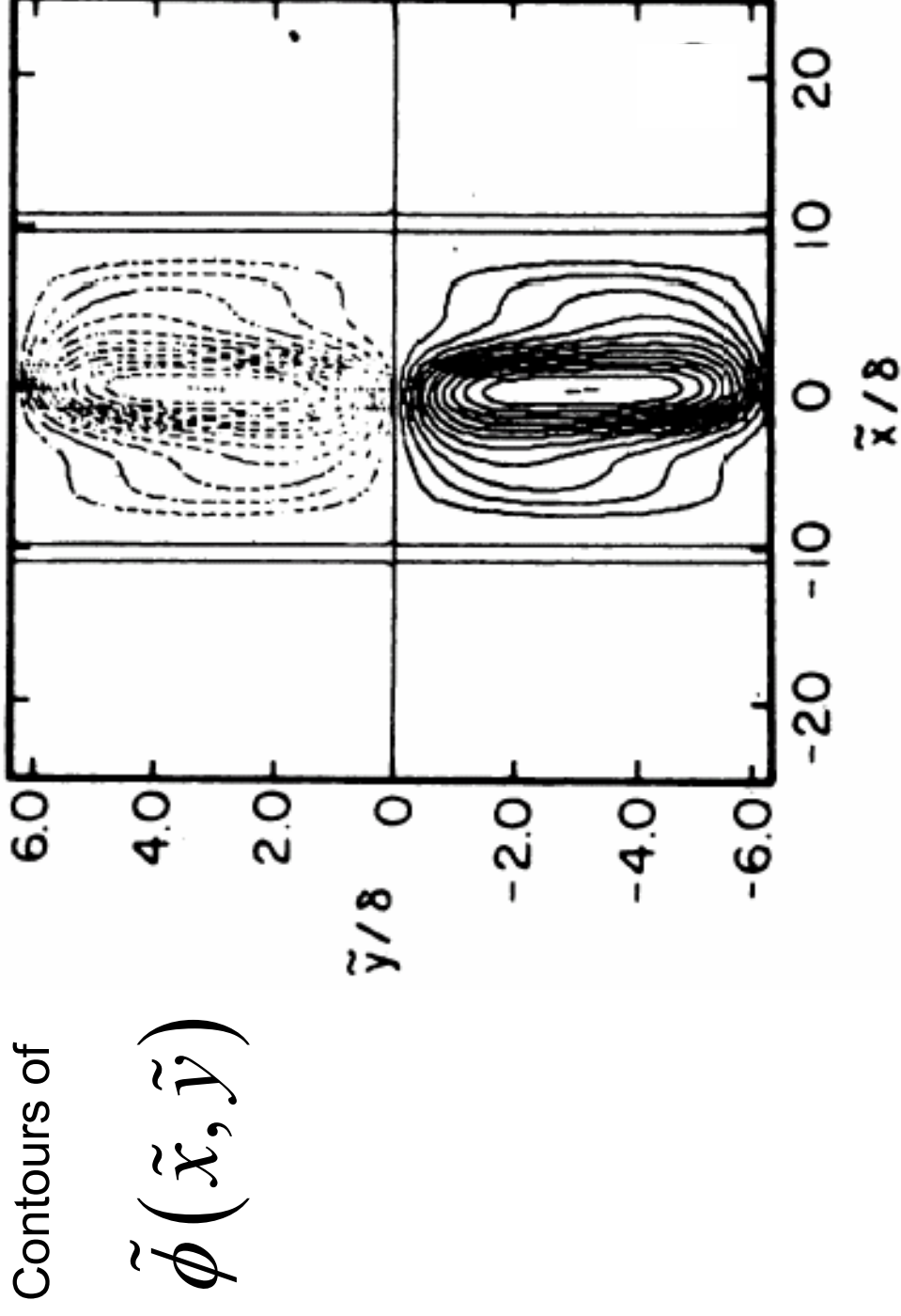


Nusselt Number

$$Nu = 1 + p_0 \langle s_1 v_{1r} \rangle / -\kappa_{\perp} T'_0$$

Resistive interchange mode

2D numerical simulation



$$D = 0.2 \quad M = 1 \quad K = 5 \times 10^{-3}$$

bifurcation

From the obvious equilibrium $\tilde{A} = \tilde{\phi} = \tilde{p} = 0$ to another equilibrium

$$\frac{\partial}{\partial \tilde{\theta}} = \frac{\partial}{\partial z} + x \frac{\partial}{\partial y} \rightarrow x \frac{\partial}{\partial y} \quad \text{in 2D}$$

$$\varepsilon^2 = \frac{1}{2} \langle |\nabla_{\perp} \tilde{\phi}|^2 \rangle$$

$$\tilde{A} = \varepsilon \hat{A} \quad \tilde{\phi} = \varepsilon \hat{\phi} \quad \tilde{p} = \varepsilon \hat{p}$$

Resistive interchange mode bifurcation analysis

$$\varepsilon \{ \hat{\phi}, \hat{A} \} = \tilde{x} \frac{\partial \hat{\phi}}{\partial \tilde{y}} + \frac{1}{R} \Delta_{\perp} \hat{A}$$

$$\varepsilon \{ \hat{\phi}, \Delta_{\perp} \hat{\phi} \} = \tilde{x} \frac{\partial}{\partial \tilde{y}} \Delta_{\perp} \hat{A} + \{ \hat{A}, \Delta_{\perp} \hat{A} \} - \frac{\partial \hat{p}}{\partial y} + M \Delta_{\perp}^2 \hat{\phi}$$

$$\varepsilon \{ \hat{\phi}, \hat{p} \} = -D \frac{\partial \hat{\phi}}{\partial y} + \chi \Delta_{\perp} \hat{p}$$

Resistive interchange mode bifurcation analysis

$$\hat{A} = \sum_{n=0}^{\infty} \hat{A}_n \varepsilon^n, \quad \dots$$

$$D = D_L + \sum_{n=0}^{\infty} D_n \varepsilon^n$$

$$L \begin{pmatrix} \hat{\phi}_0 \\ \hat{p}_0 \end{pmatrix} \equiv \begin{pmatrix} -R\tilde{x}^2 \partial^2 \hat{\phi}_0 / \partial \tilde{y}^2 - \partial \hat{p}_0 / \partial \tilde{y} + M \Delta_{\perp}^2 \hat{\phi}_0 \\ \partial \hat{\phi}_0 / \partial \tilde{y} - (\chi / D_L) \Delta_{\perp} \hat{p}_0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

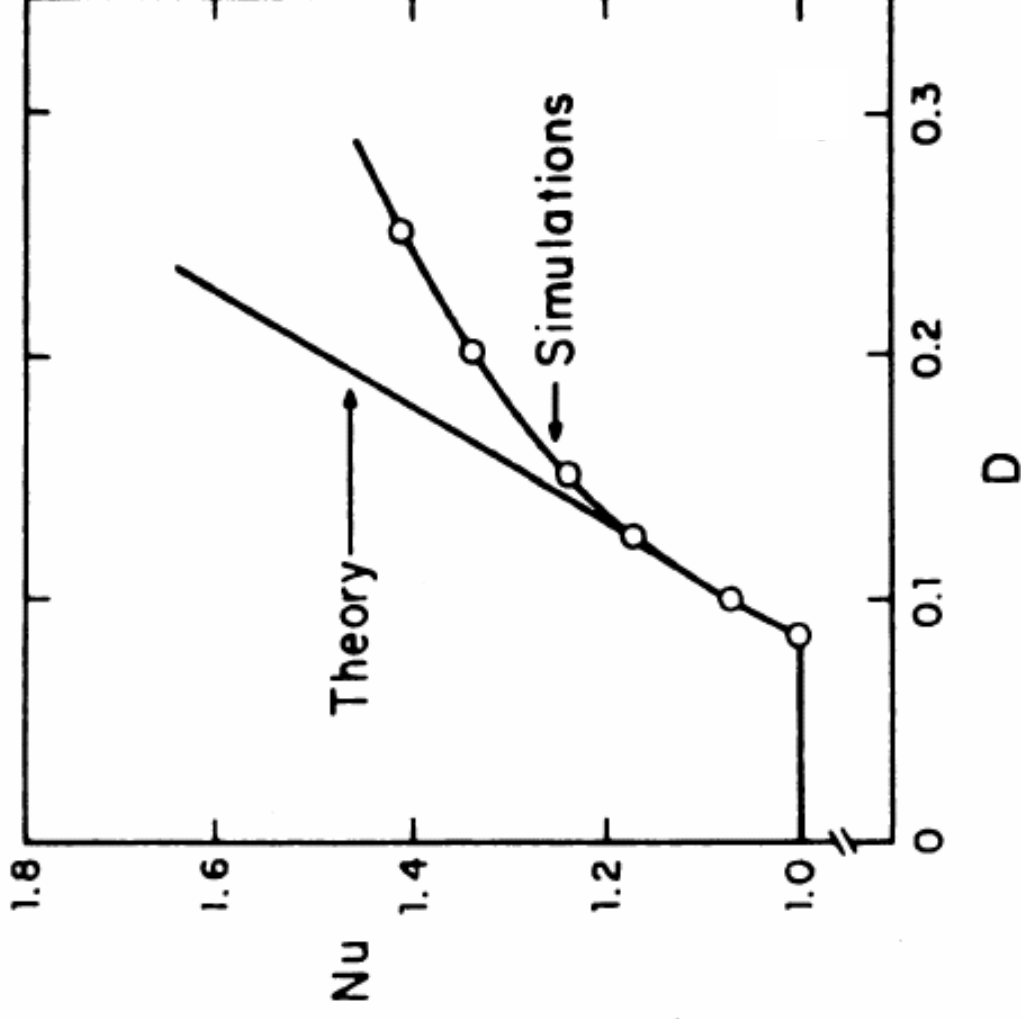
Resistive interchange mode bifurcation analysis

$$D_1 = 0 \quad D = D_L + D_2 \varepsilon^2 + \dots$$

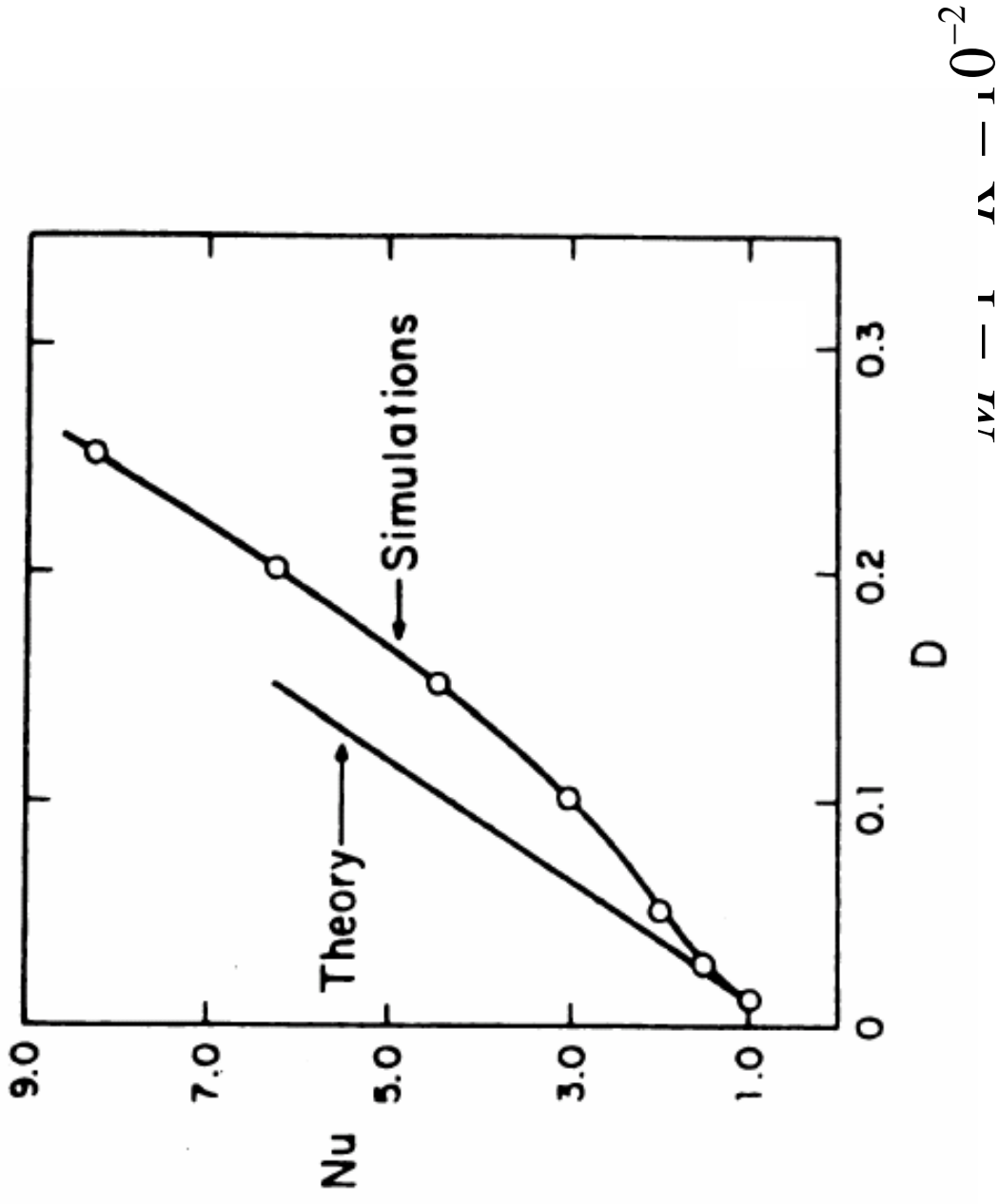
$$p_0 \langle s_1 v_{1r} \rangle = - \frac{B_\theta B^2 \sigma^2}{(\gamma - 1) \sqrt{\rho_0}} k \langle \hat{p}_{01} \hat{\phi}_{01} \rangle \frac{D - D_L}{D_2}$$

$$\text{Nusselt Number} \quad Nu = 1 + p_0 \langle s_1 v_{1r} \rangle / -\kappa_\perp T'_0$$

Resistive interchange mode bifurcation analysis and 2D nonlinear simulation



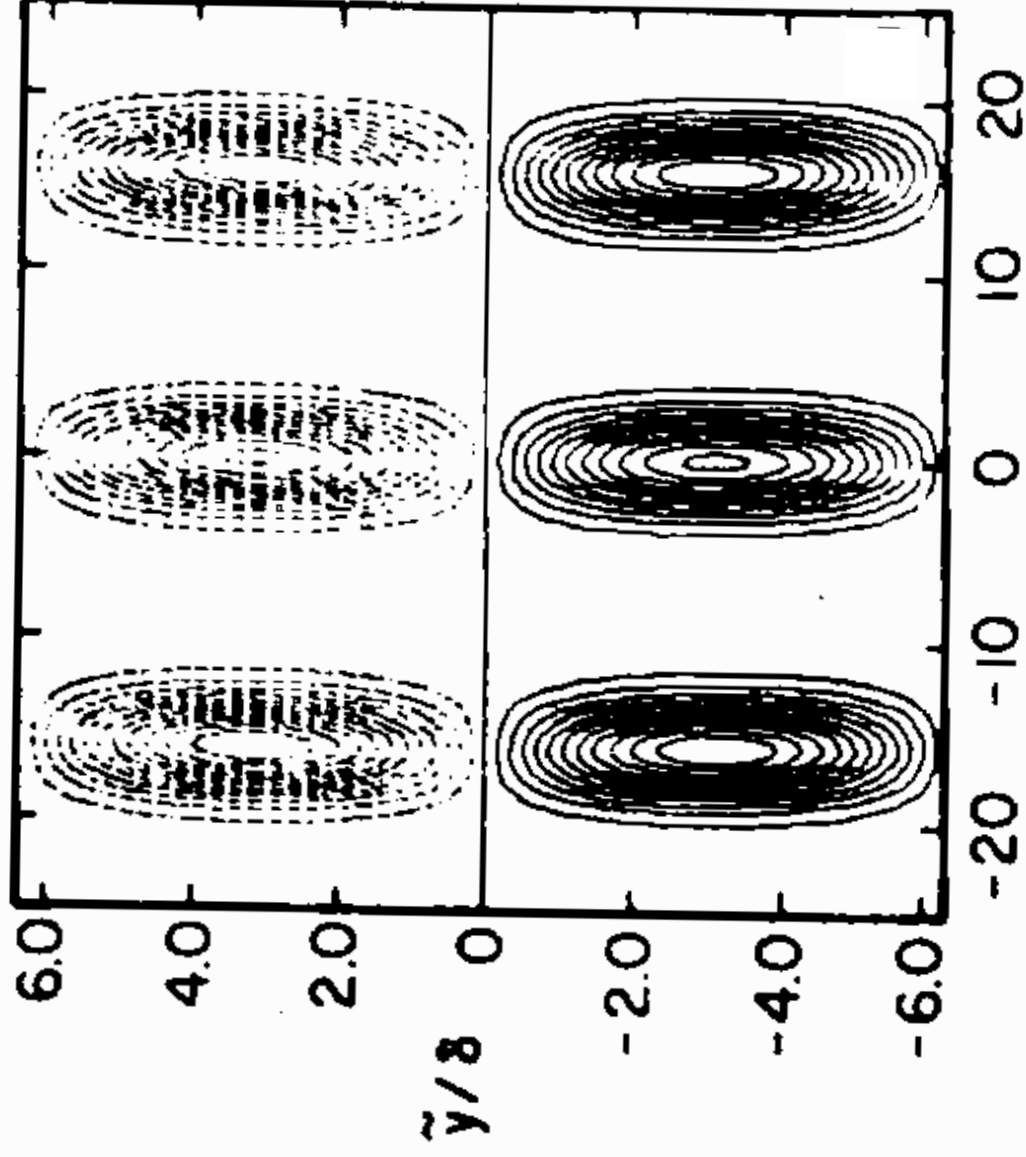
Resistive interchange mode bifurcation analysis and 2D nonlinear simulation



$$\nu = 1 \quad \lambda = 10^{-2}$$

Resistive interchange mode

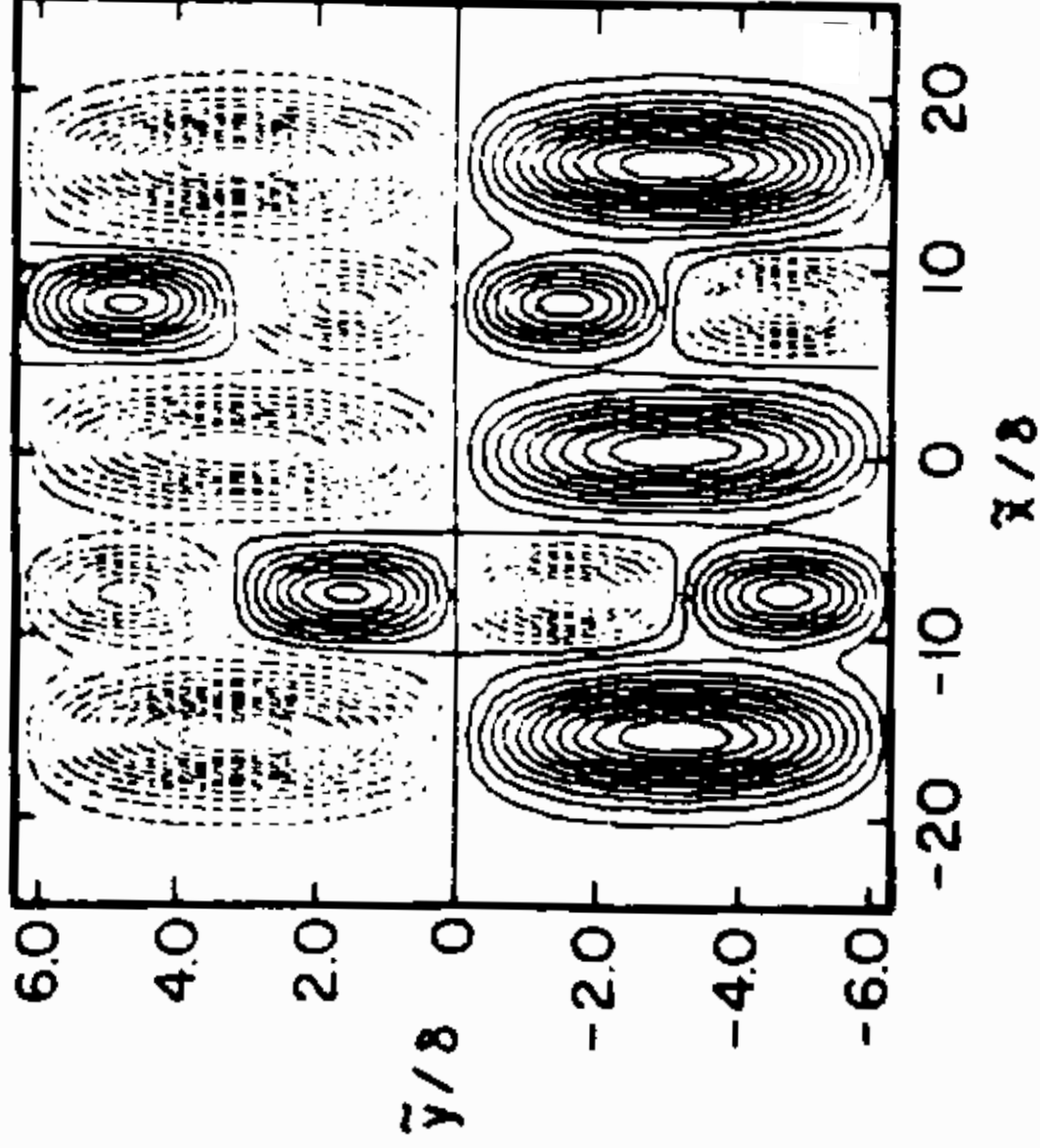
3D nonlinear simulation



$\tilde{x}/8 D = 0.15 \quad M = 1 \quad K = 6 \times 10^{-2}$

Resistive interchange mode

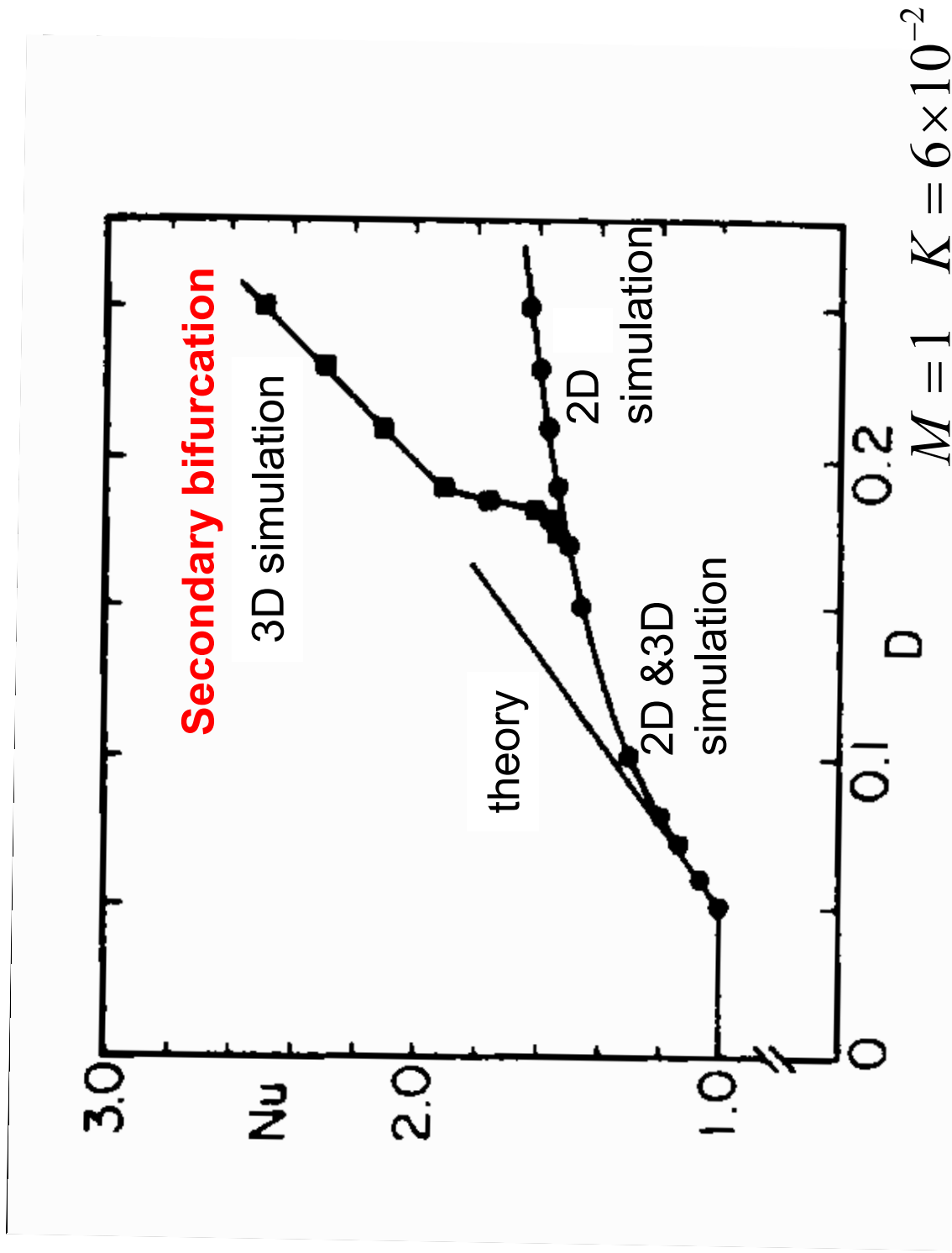
3D nonlinear simulation



$$D = 0.23 \quad M = 1 \quad K = 6 \times 10^{-2}$$

Resistive interchange mode

Comparison btw 2D and 3D nonlinear simulations



practical issues
for resistive interchange modes
and resistive ballooning modes

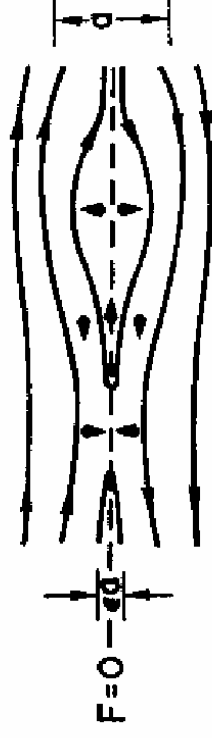
- **strongly nonlinear evolution and turbulence**
- **effects of sheared flows on nonlinear modes**
- **flow generation from turbulence**
- **intermittent bursts of transport**
- **...**

Nonlinear evolution of tearing modes with multiple rational surfaces

Tearing mode equations

$$\frac{d\tilde{A}}{d\tau} = \frac{\partial\tilde{\phi}}{\partial\theta} + \frac{1}{R}\Delta_{\perp}\tilde{A}$$

$$\frac{d}{d\tau}\Delta_{\perp}\tilde{\phi} = \frac{\partial}{\partial\theta}\Delta_{\perp}\tilde{A} + \{\tilde{A}, \Delta_{\perp}\tilde{A}\} + M\Delta_{\perp}^2\tilde{\phi}$$

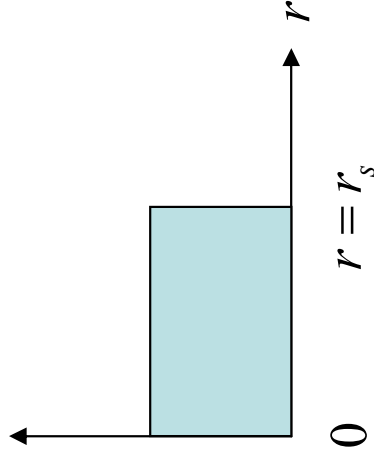


tearing mode

“m=1 tearing mode”, “resistive kink mode”

$$\gamma = [q'(r_s) k r_s^2 S]^{2/3} \tau_R^{-1} \propto \eta^{1/3} q'^{2/3}$$

mode structure



$$q(r) = \frac{r B_t}{R B_p}$$

safety factor

$$S = \tau_R / \tau_A$$

magnetic Reynolds number

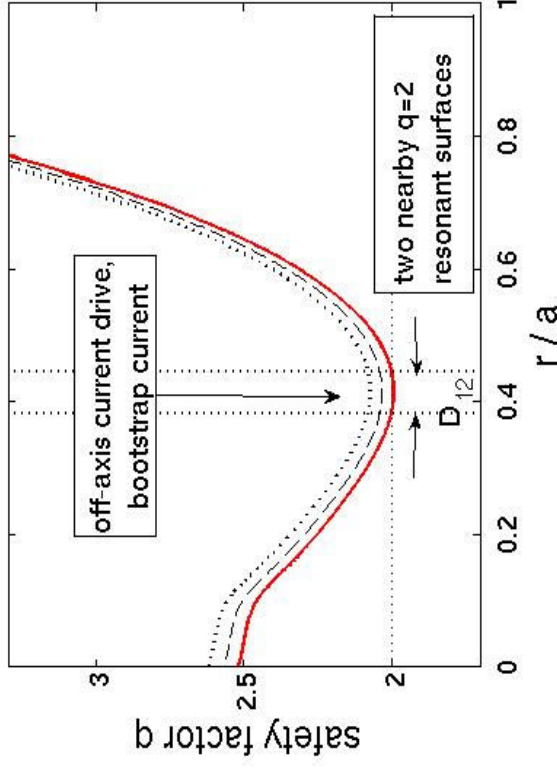
$$\tau_R = a^2 / \eta$$

resistive skin time

$$\tau_A = a / V_A \quad V_A = B_t / \sqrt{\rho_0}$$

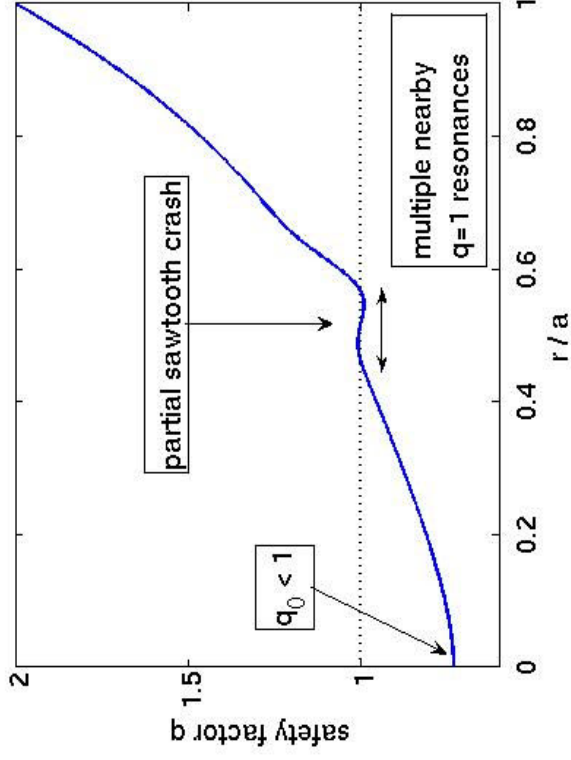
Alfvén transit time

multiple tearing modes



Multiple $q=m/n$ resonant surfaces may occur with a small distance apart

← Advanced reversed-shear tokamak & two resonant surfaces near q_{\min}

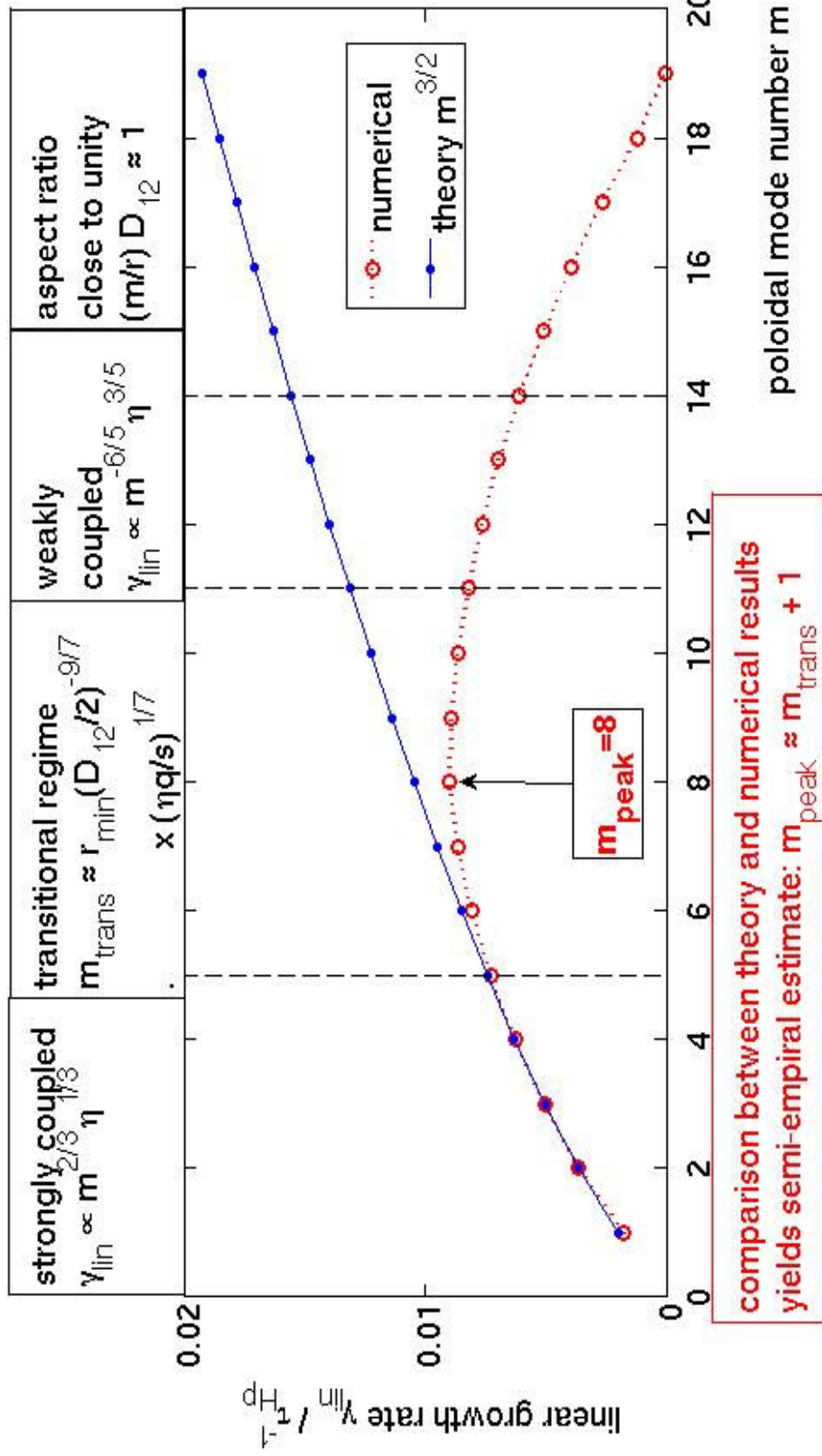


← Partial sawtooth collapse with $q_0 < 1$ and $q \sim 1$ in an annular region

Multiple Tearing Modes (MTM) may become unstable

Linear stability analyses: growth rate vs. poloidal mode number

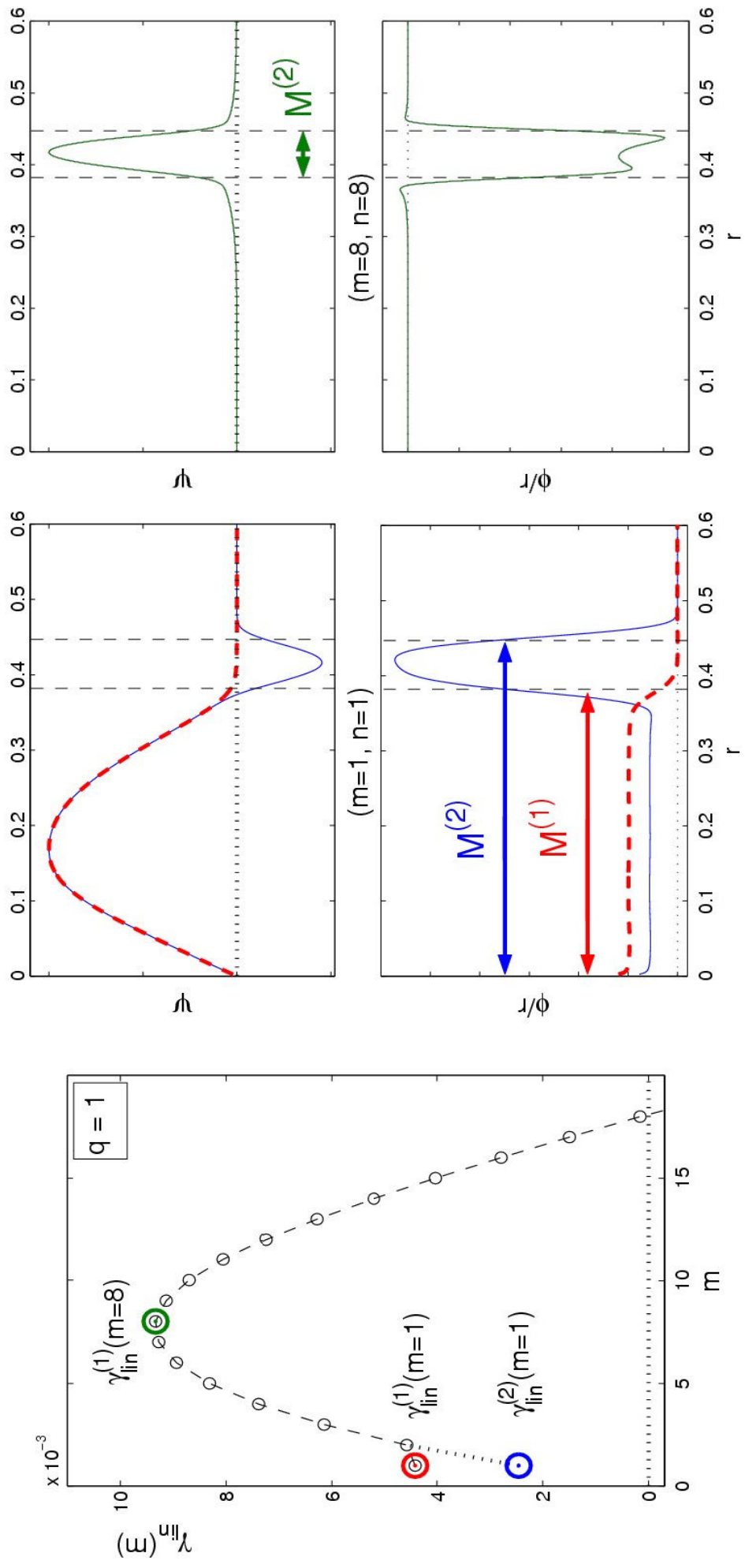
resistive $q=1$ Double Tearing Mode (DTM)



• Theory [Pritchett et al. 1980] and numerical results agree

• Broad spectrum, dominant high- m modes

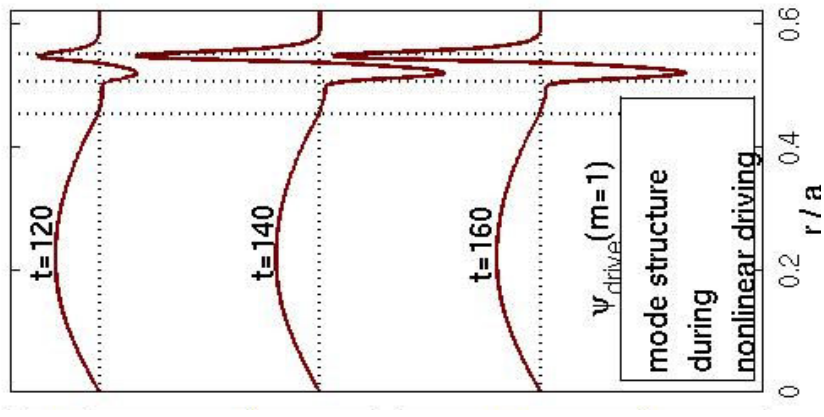
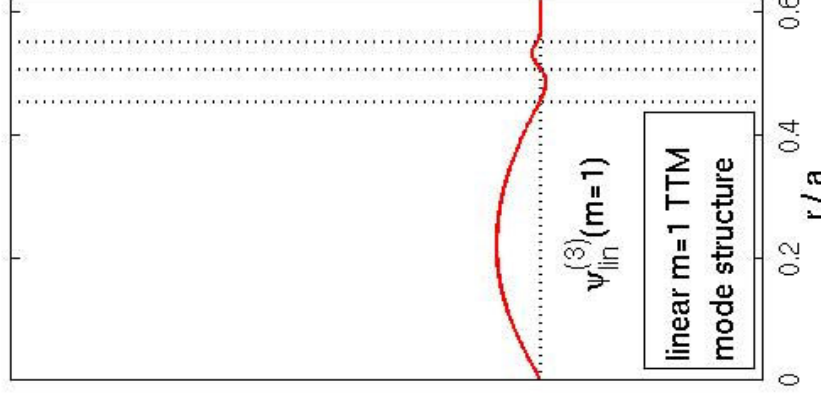
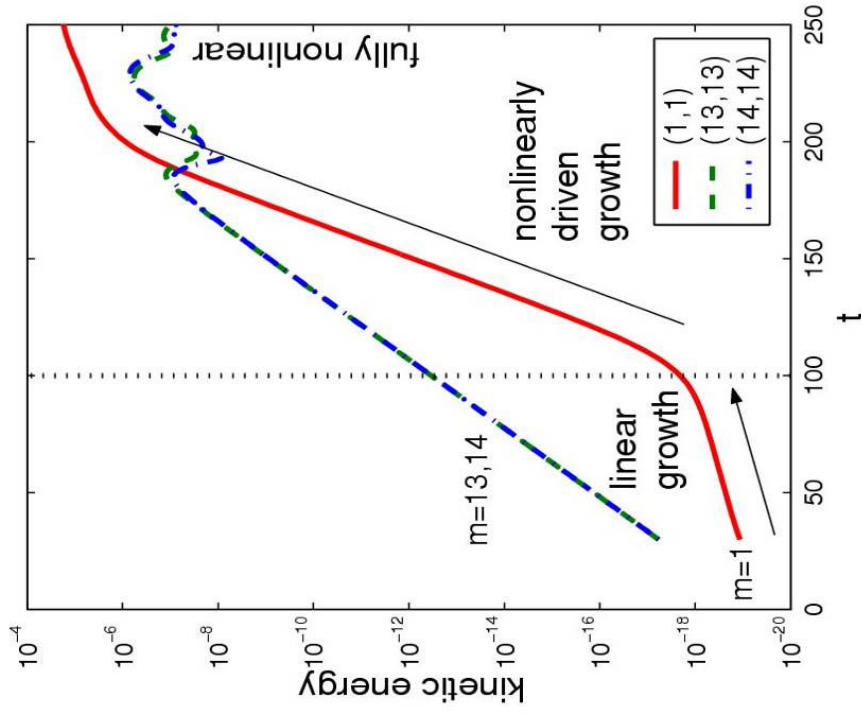
Linear stability analyses: mode structures



$m=1$ double kink-tearing mode, $m>1$ coupled tearing modes

Nonlinear drive of $m=1$ mode (fast trigger)

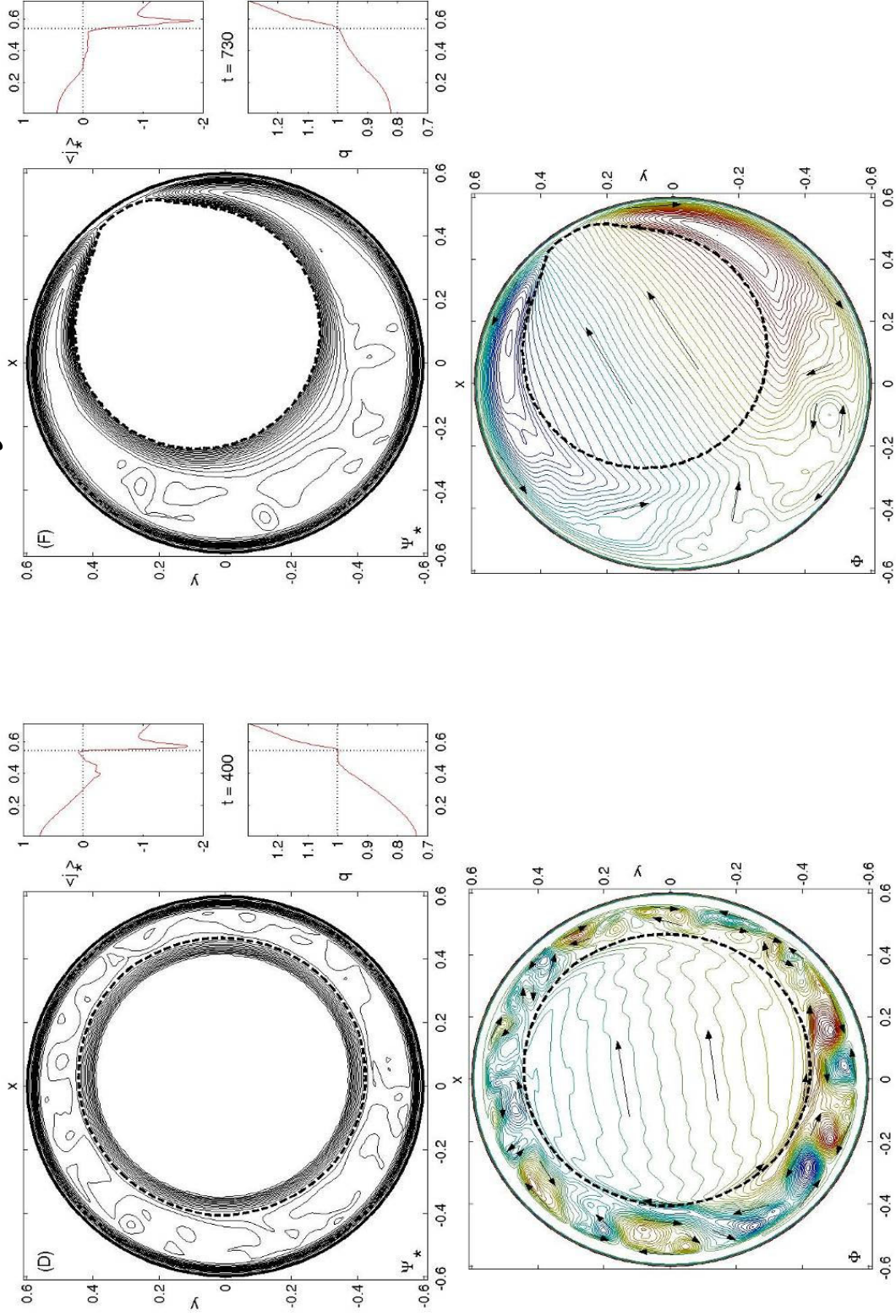
Triple Tearing Modes (TTM) drive resistive kink



- Growth rate switches from $\gamma_{lin}(m=1)$ to about $2 \gamma_{lin}(m_{peak})$
- Nonlinear drive local, but mode structure remains global

Sawtooth crash: *Interaction with kink*

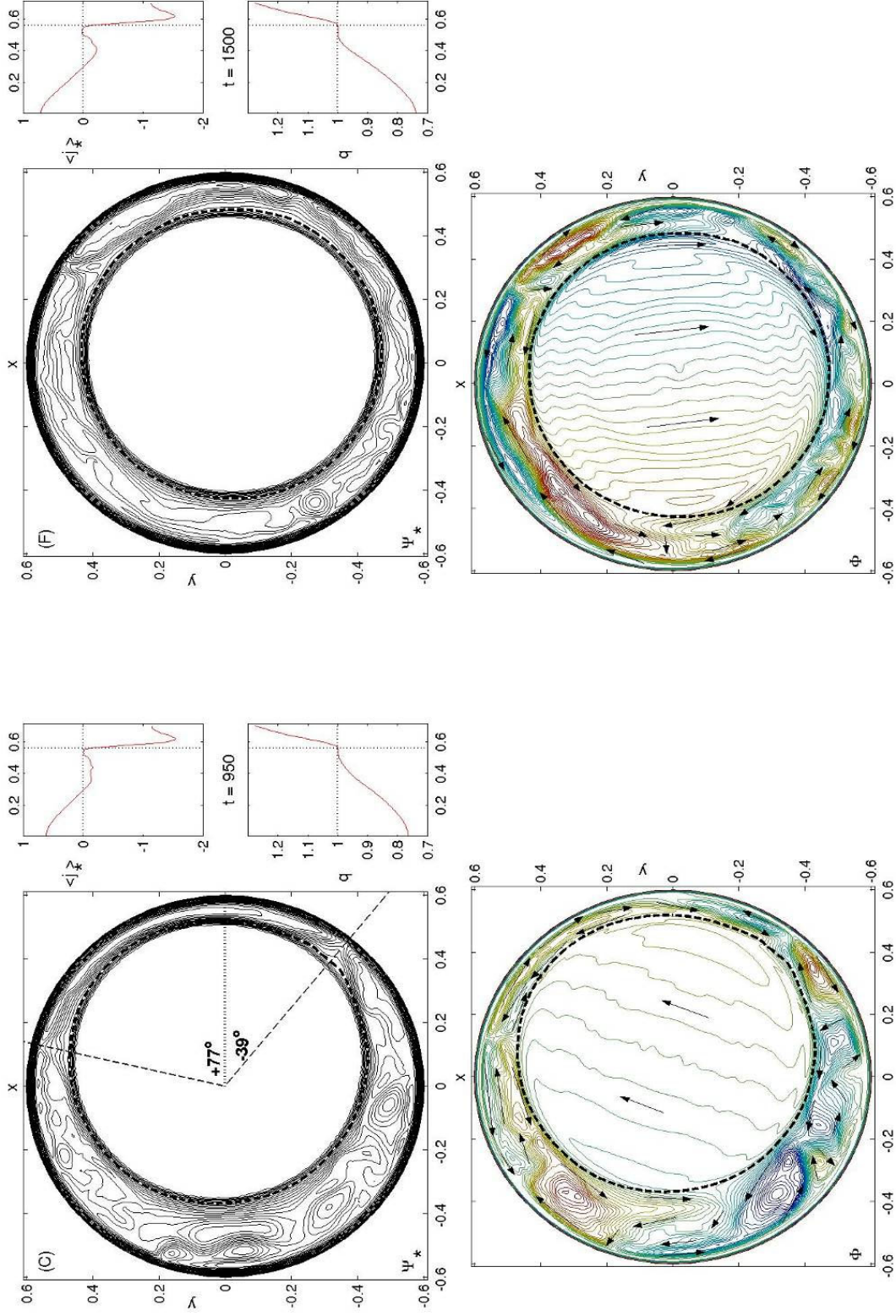
Internal kink surrounded by MHD turbulence



• *Direction of kink flow fluctuates, crash may be delayed*

Sawtooth crash: *Partial reconnection*

Internal kink surrounded by MHD turbulence



• *In some cases, the kink saturates and decays temporarily*

Summary

- Gravitational driven instabilities of fluids: Rayleigh Taylor instability and Rayleigh Bénard instability (convection)
- Similar instability for magnetically confined plasmas: Resistive interchange instability (Resistive g-mode)
- Nonlinear saturation and bifurcation of resistive interchange instability
- Another example of nonlinear evolution and turbulence : Nonlinear evolution of double and triple tearing modes

Acknowledgements

E. Hameiri, W. Horton, A. Bierwage,
S. Benkadda, and M. Wakatani

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theorem

Suppose the range of linear operator L is closed. Then the inhomogeneous equation

$$L\mathbf{x} = \mathbf{a}$$

has a solution if and only if \mathbf{a} is orthogonal to all solutions \mathbf{z} of

$$L^*\mathbf{z} = \mathbf{0}$$

with L^* being the adjoint operator of L .